

PITH ESTIMATION ON ROUGH LOG END IMAGES USING LOCAL FOURIER SPECTRUM ANALYSIS

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University of Salzburg

1) INTRODUCTION

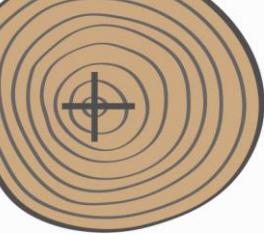
2) PITH ESTIMATION SCHEME

LOCAL FOURIER SPECTRUM ANALYSIS METHODS

BLOCK SELECTION ALGORITHMS

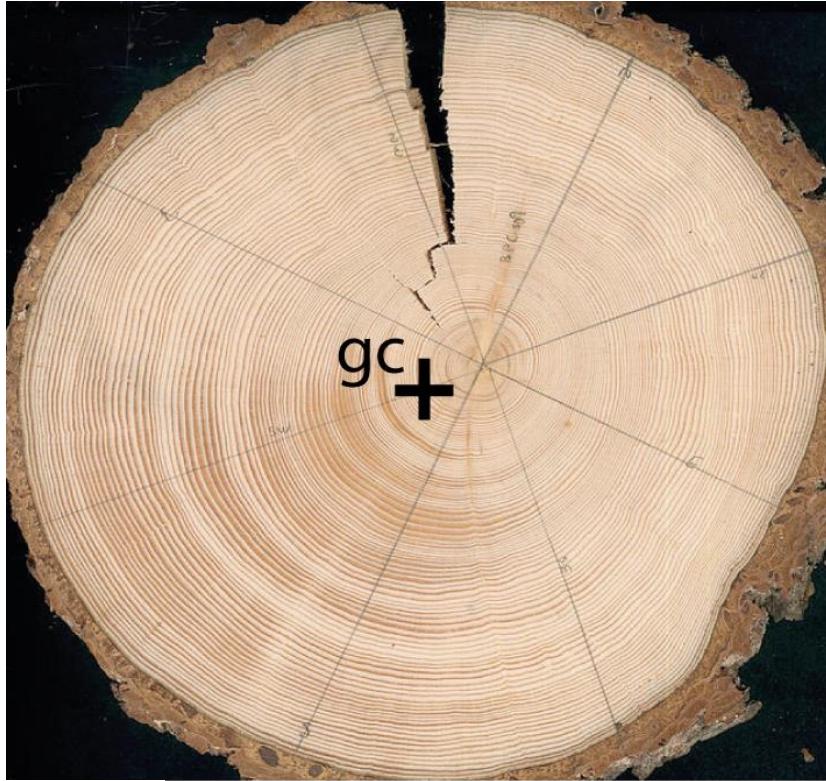
3) EXPERIMENTS & RESULTS

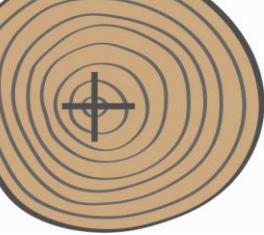




PITH ?

- Growth center of a tree stem == innermost point
- Pith != geometric center





WHY ?

Single reference point on a cross section image

Timber Grading

Fingerprint Approach

Wood industry

- Annual ring measurements:
→ counting / average ring width
- Reaction wood estimation

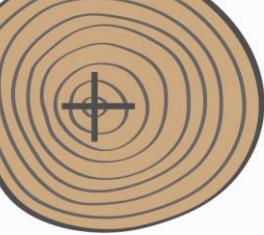
Dendrochronology:

- Tree ring dating



Pith estimation scheme

Experiments

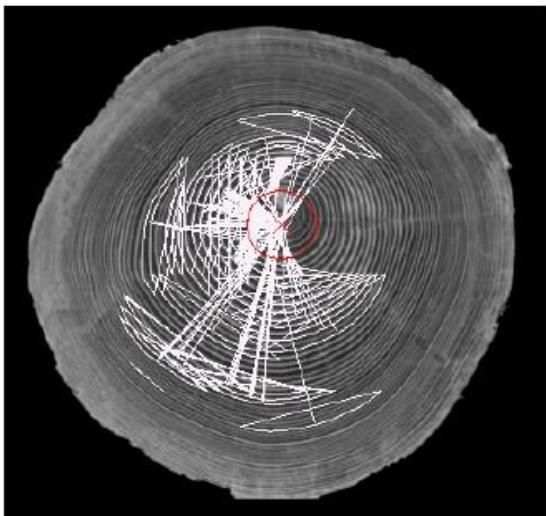


RELATED LITERATURE

Annual Ring Analysis

F. Longuetaud, J.-M. Leban, F. Mothe, E. Kerrien, and M.-O. Berger, “**Automatic detection of pith on ct images of spruce logs**”, 2004

K. Entacher, S. Hegenbart, J. Kerschbaumer, C. Lenz, D. Planitzer, M. Seidel, A. Uhl, and R. Weiglmaier, “**Pith detection on ct-cross-section images of logs: An experimental comparison**”, 2008

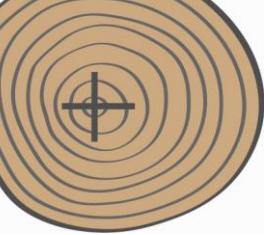


Local Orientation Estimation

T. Hanning, R. Kickingereder, and D. Casasent, “**Determining the average annual ring width on the front side of Lumber**”, 2003.

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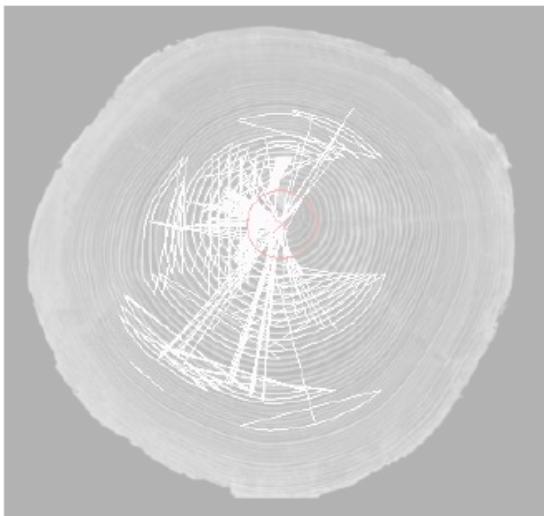


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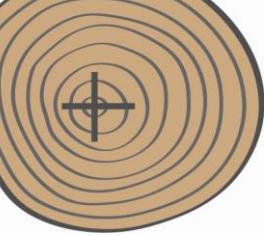


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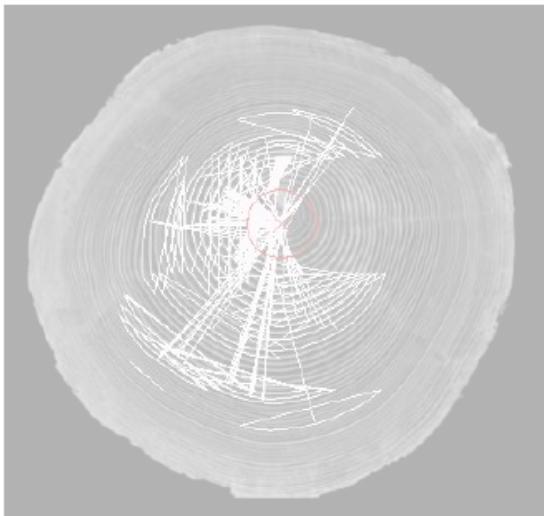


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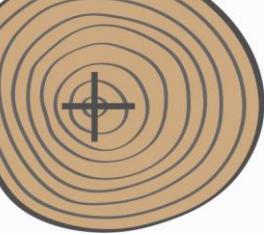
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→ First work treating rough log end images

→ Local orientation estimation using
- Laplacian pyramids and linear
symmetry
- Quadrature filters

???



Contributions

→ Large image set captured at an Austrian sawmill yard

→ Comparative experiments (ct-images and rough log end images)

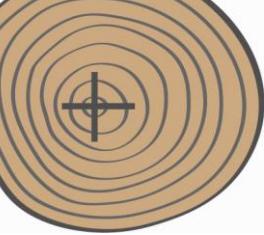
- 109 images log rough spruce log ends ↔ (Norell, 2008)
- 29 ct-image slices of a single log ↔ (Entacher, 2008)

→ Simple Fourier Spectrum Analysis methods

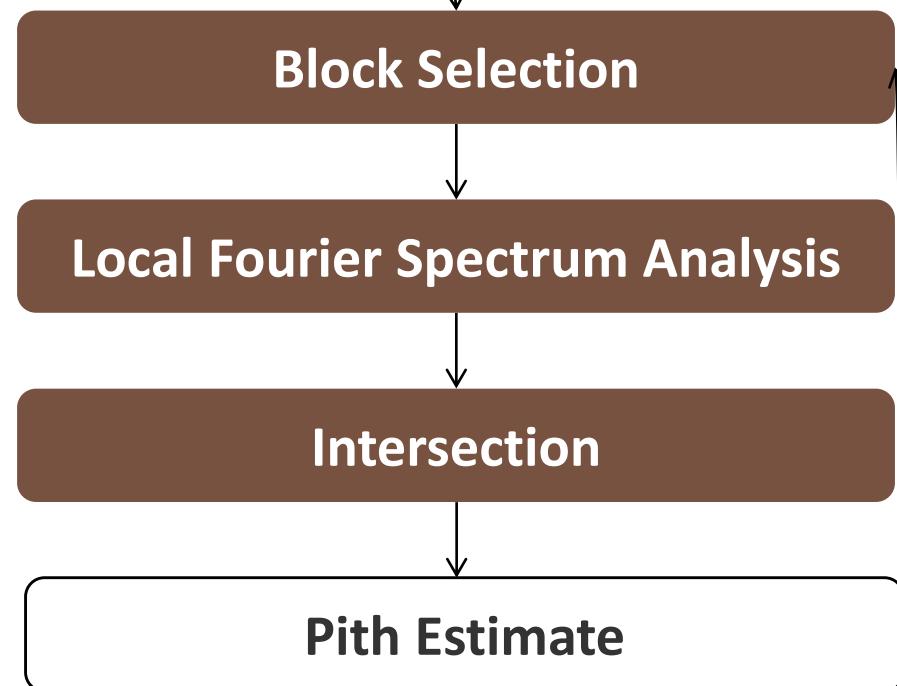
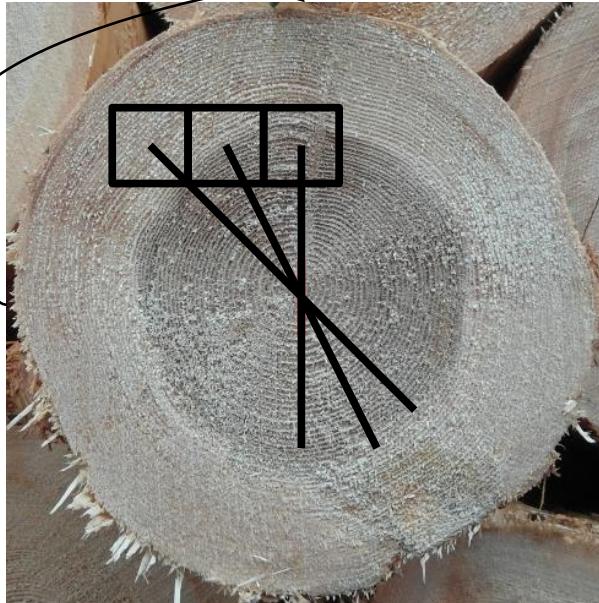
- considerations about Fourier Spectra of annual ring sections

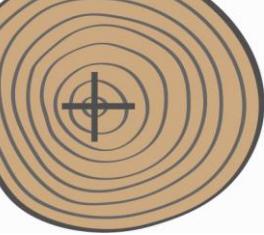
→ Pith estimation accuracy and timing performance:

- Block selection (size and distribution)



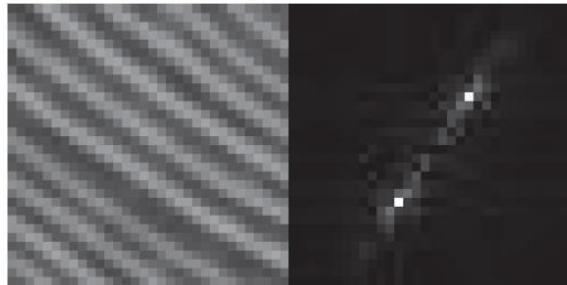
Pith estimation scheme



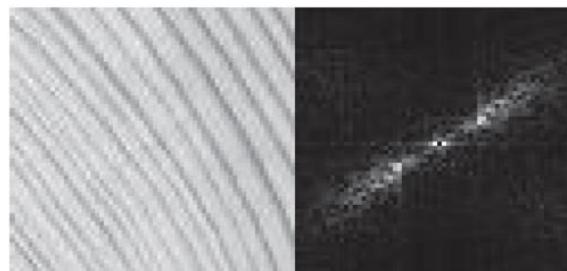


Pith estimation scheme

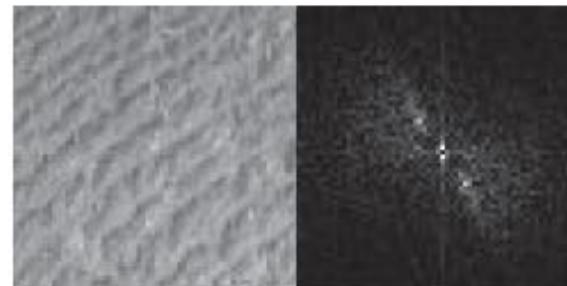
Local Fourier Spectrum Analysis



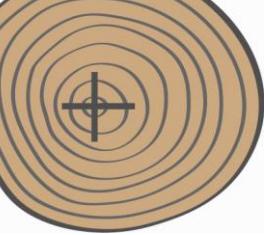
→ ct-image
varying ring width



→ sanded cross section
ring curvature

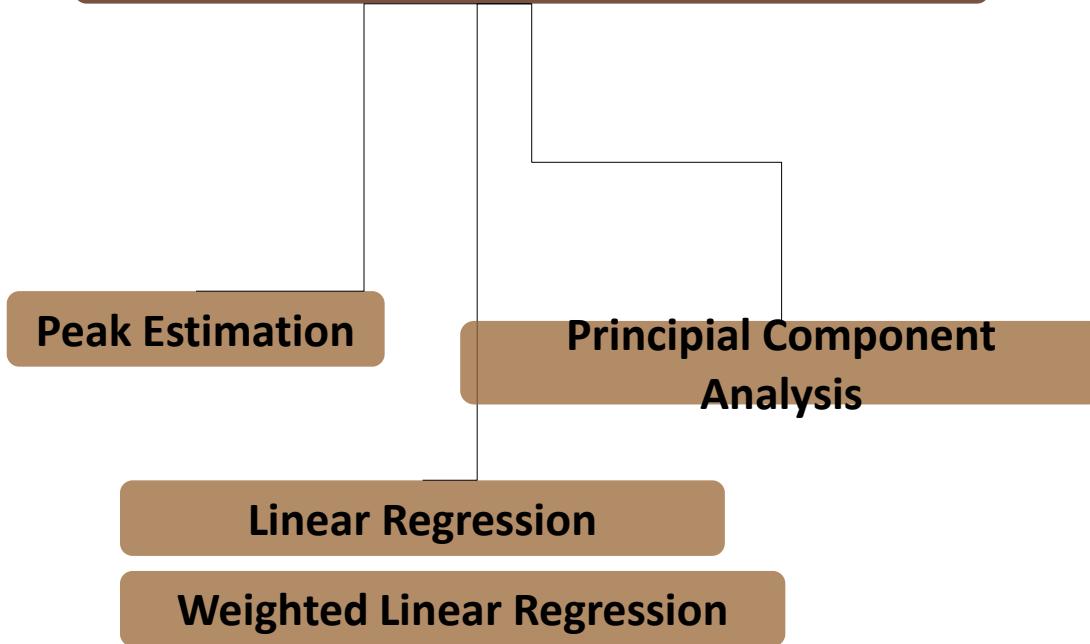


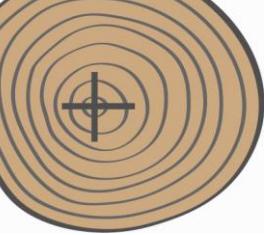
→ rough cross section
sawing disturbances



Pith estimation scheme

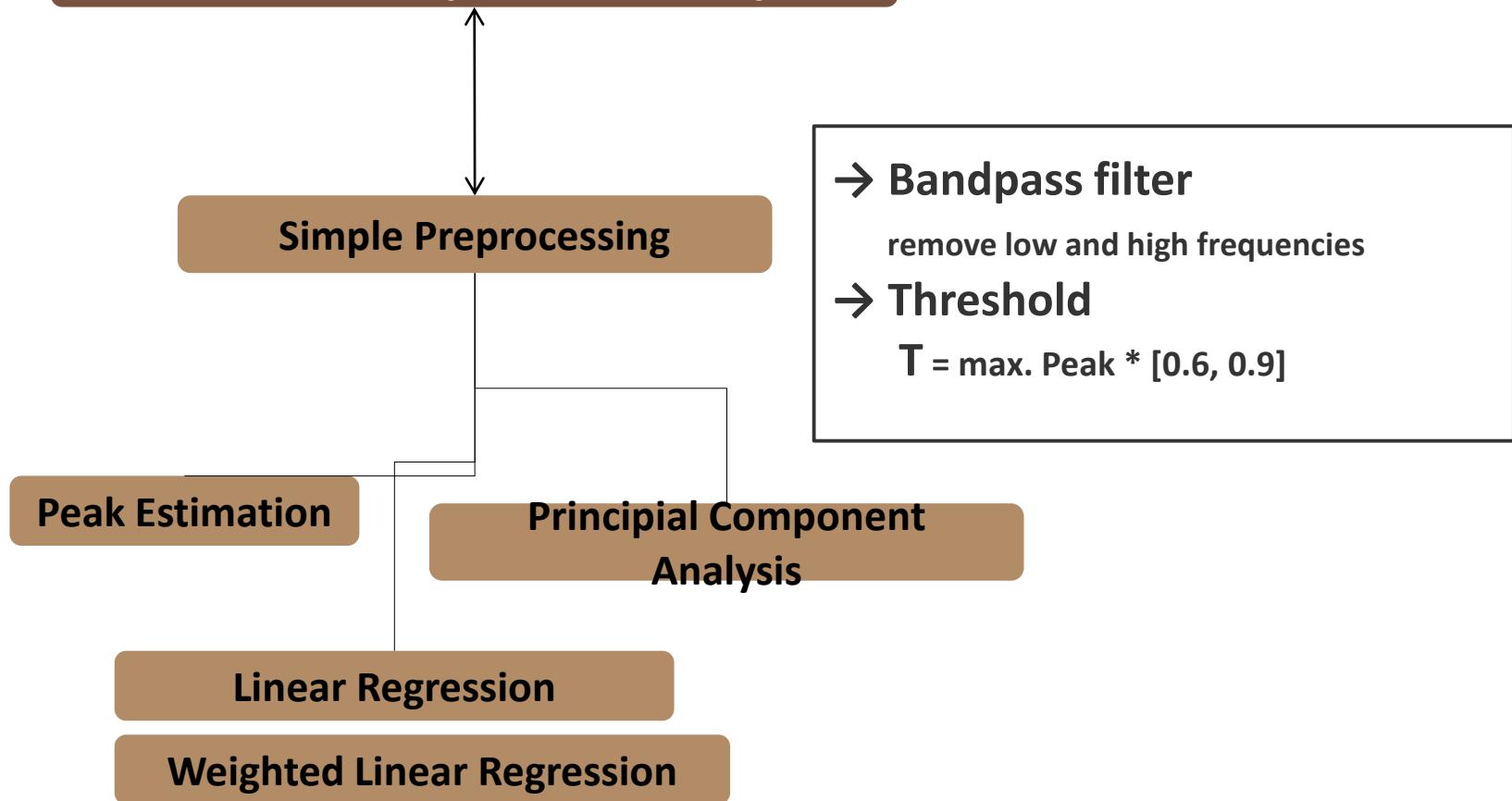
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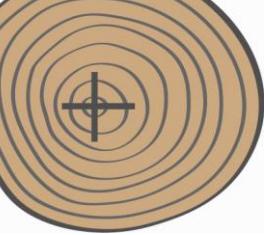




Pith estimation scheme

Local Fourier Spectrum Analysis

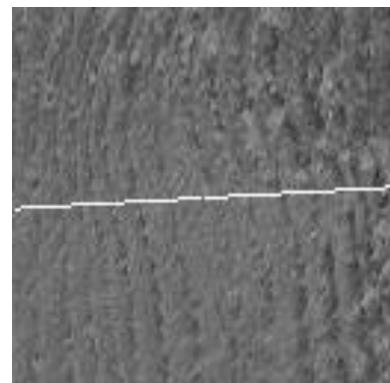




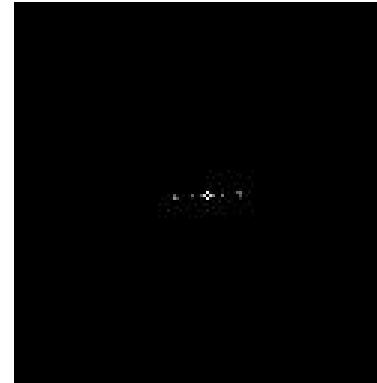
Pith estimation scheme

Local Fourier Spectrum Analysis

PCA

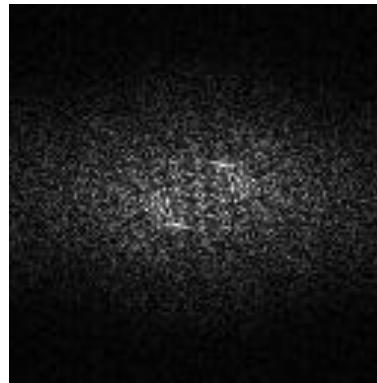
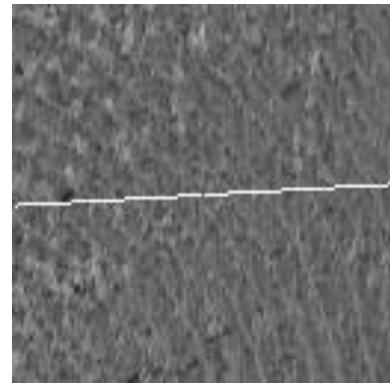


$$T = \text{max. Peak} * 0.6$$



Certainty Value:

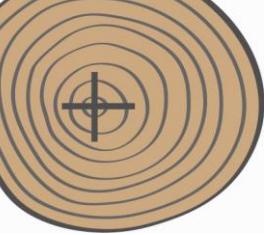
0,995



0,769

Introduction

Experiments

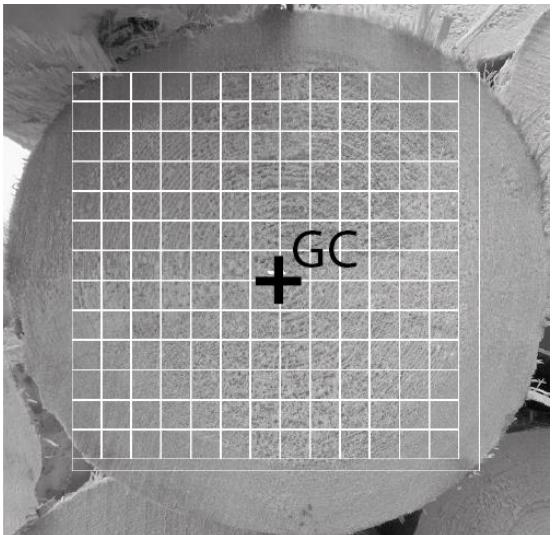


Pith estimation scheme

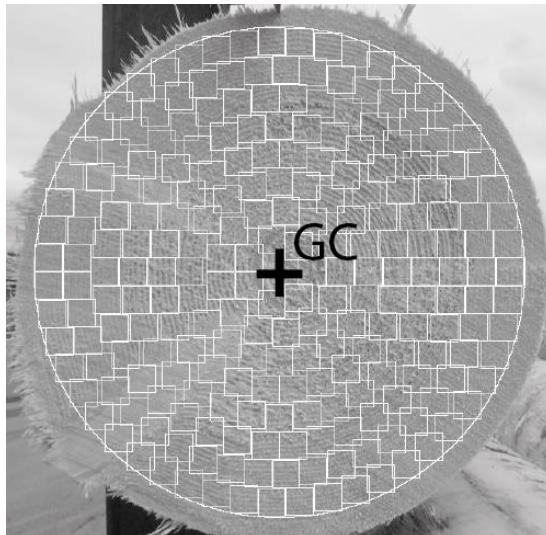
Block Selection Algorithms

Block Area Selection

Rectangular

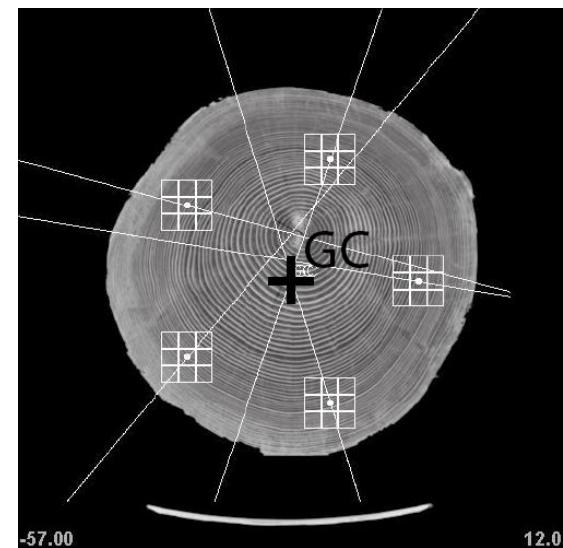


Circular



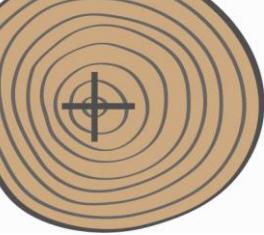
Pointwise Block Selection

(Österberg, 2004)



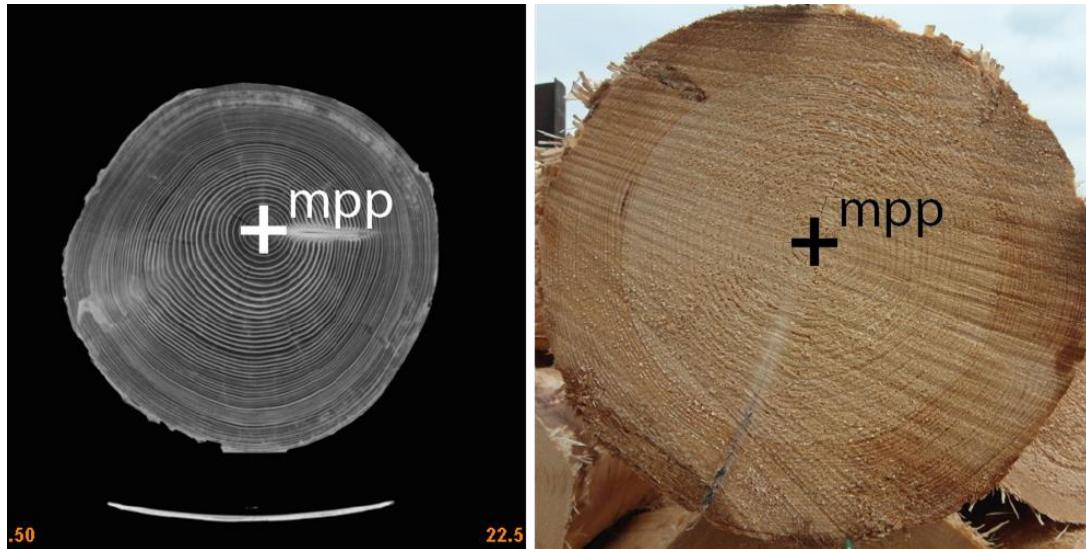
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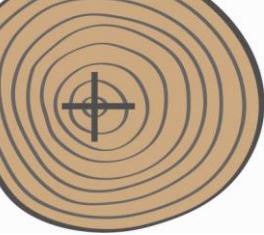


Experiments

→ Two image sets



→ 36 ct – image slices (512x512)
→ 109 rough log end images (1024x768)



Experiments

→ Two image sets

→ Different configurations:

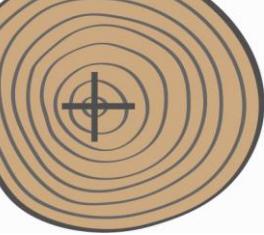
- Two block selection algorithms with different settings

Block Area Selection

- Circular and rectangular
- Blocksize 8x8 to 32x32
- non- and halfoverlapping
- different selection areas

Pointwise Block Selection

- Blocksize 8x8 to 32x32
- Cluster size
- Amount of clusters
- Termination criterias



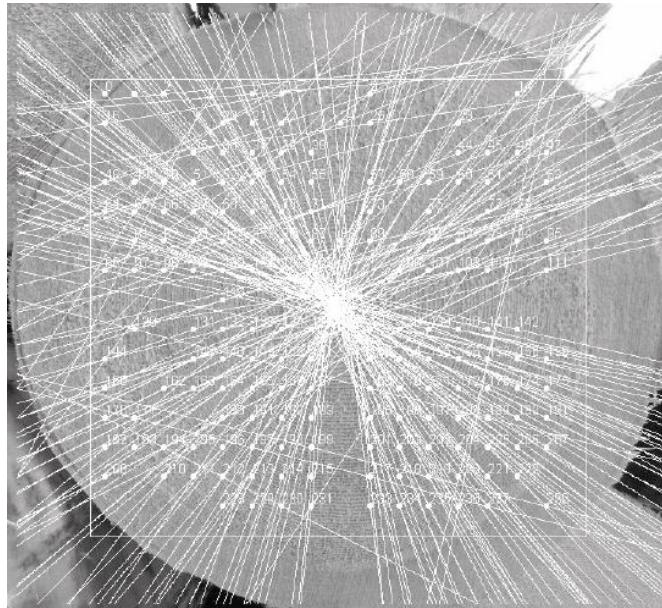
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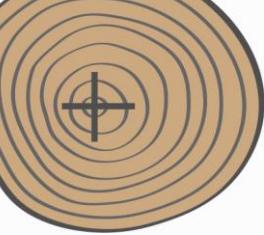
→ Two image sets

→ Different configurations:

- Two block selection algorithms with different settings

→ Different certainty value thresholds for the intersection step

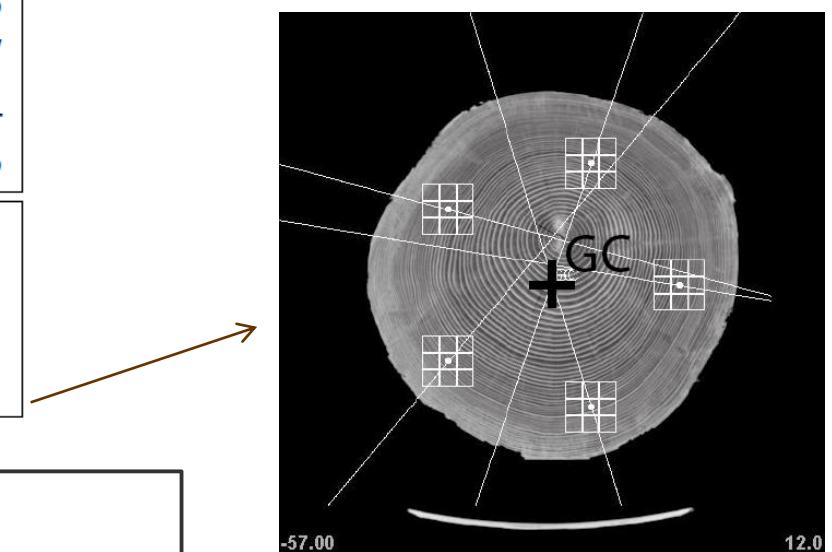


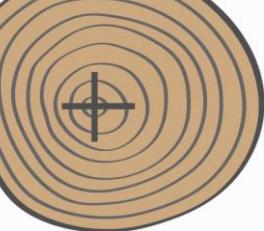


Experiments

Config.	Method	C	Mean	StDev	#B	R	[ms]
CT-BAS-C1	PA	-	4.65	1.12	249	6	211
	LSR	0.9	4.86	1.3	234	7	196
	WLSR	0.9	4.78	1.25	243	7	202
	PCA	0.9	4.78	1.19	230	7	199
CT-BAS-C2	PA	-	3.08	1.68	346	7	303
	LSR	0.5	2.27	1.0	330	4	307
	WLSR	0.9	2.41	1.1	339	5	304
	PCA	0.7	2.46	1.35	335	6	303
CT-PBS-C3	PA	-	6.54	8.55	117	45	21
	LSR	0.9	2.16	1.75	118	8	22
	WLSR	0.9	1.86	1.3	114	5	21
	PCA	0.7	1.49	1.06	111	4	21

→ CT-BAS-C1 (16x16 blocksize, non-overlapping)
 → CT-BAS-C2 (8x8 blocksize, non-overlapping) – 80x80
 → CT-BAS-C3
 (16x16 blocksize, 5 clusters – 2x2 blocks,
 max. 5 iterations, termination criteria: 2 pixel)





Experiments

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CT-BAS-C1	PA	-	4.65	1.12	249	6	211
	LSR	0.9	4.86	1.3	234	7	196
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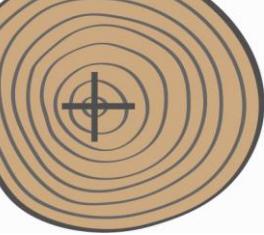


METHOD	AVG. TIME
Circle Equation (ring tracing - CErt)	1.25
Circle Equation (equal gradients - CEeg)	16.64
Gradient Method (intersection - GMI)	6.17
Gradient Method (radial length - GMrl)	3.16
Curvature (Cur)	1.40
Poincaré Index (Poi)	1.04



Mean - 2.8 pixel

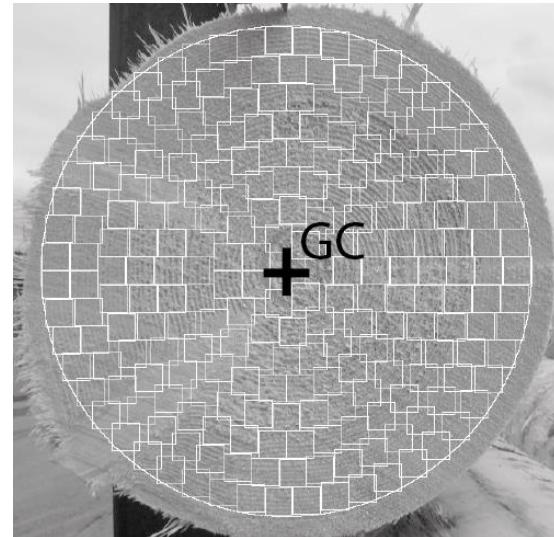
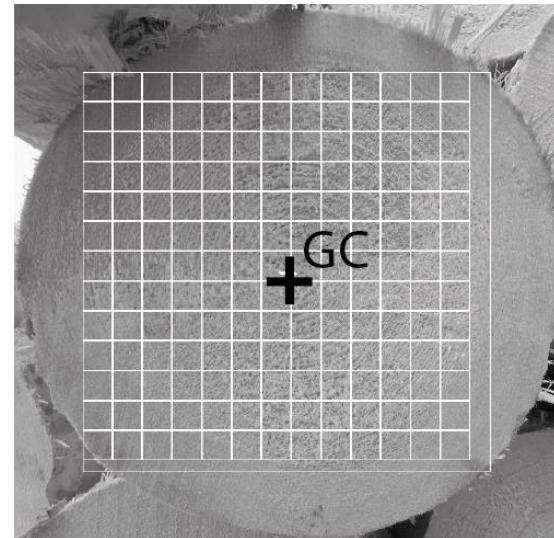
(Entacher,2008)

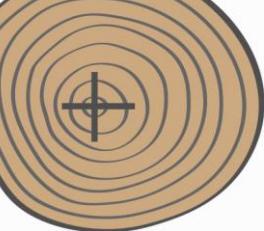


Experiments

16x16 pixel blocks

Config		Method	C	Mean	StDev	#B	R	[ms]
Rectangular BAS-1	non overlapping	PA	-	5.56	4.43	710	25	1048
	LSR	0.9	6.45	5.08	643	27	1008	
	WLSR	0.9	6.49	5.09	689	31	1032	
	PCA	0.5	5.75	4.3	660	25	1036	
	half overlapping	PA	-	3.49	2.53	2789	13	2453
	LSR	0.9	4.36	4.01	2528	24	2306	
	WLSR	0.9	4.2	3.81	2709	25	2357	
	PCA	0.9	4.03	3.23	1697	15	2003	
Circular BAS	non overlapping	PA	-	6.57	4.55	798	22	1053
	LSR	0.9	6.0	4.7	720	27	960	
	WLSR	0.9	6.43	5.56	481	34	858	
	PCA	0.9	6.02	5.25	310	33	818	
	half overlapping	PA	-	3.73	3.15	2118	20	1969
	LSR	0.9	4.43	4.39	1923	30	1888	
	WLSR	0.5	4.19	4.25	2097	30	1962	
	PCA	0.9	4.39	3.77	1296	25	1650	
	non	PA	-	4.67	3.05	321	17	768



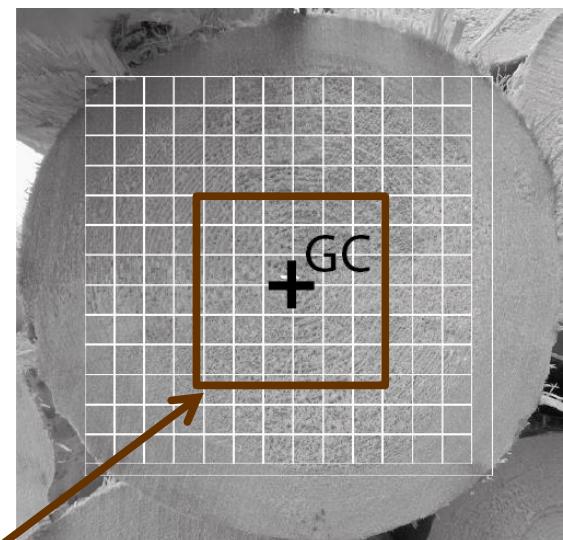


Experiments

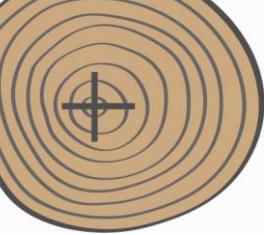
Config	Method	C	Mean	StDev	#B	R	[ms]	
Rectangular BAS-1	non overlapping	PA	-	5.56	4.43	710	25	1048
	overlapping	LSR	0.9	6.45	5.08	643	27	1008
		WLSR	0.9	6.49	5.09	689	31	1032
		PCA	0.5	5.75	4.3	660	25	1036
	half overlapping	PA	-	3.49	2.53	2789	13	2453
		LSR	0.9	4.36	4.01	2528	24	2306
		WLSR	0.9	4.2	3.81	2709	25	2357
		PCA	0.9	4.03	3.23	1697	15	2003

Config	Method	C	Mean	StDev	#B	R	[ms]	
Rectangular BAS-2	non overlapping	PA	-	4.67	3.05	321	17	768
	overlapping	LSR	0.9	5.91	5.1	295	33	761
		WLSR	0.5	6.46	6.7	319	45	771
		PCA	0.7	5.45	4.2	262	21	749
	half overlapping	PA	-	3.04	2.43	1284	13	1393
		LSR	0.9	3.38	3.37	1178	19	1355
		WLSR	0.3	3.01	2.49	1279	15	1396
		PCA	0.9	3.1	2.34	785	11	1193

PBS	20 - Cluster	PA	0.9	6.87	7.38	417	65	150
		LSR	0.7	8.19	9.1	390	50	178
		WLSR	0.7	8.37	9.53	402	48	184
		PCA	0.9	6.23	7.22	299	54	229



300x300 pixel



Conclusions

- Fourier Spectrum Analysis methods: fast, robust → accurate pith estimation
- different image sets require different configurations
 - difficulties due to disturbances
- Peak analysis is very simple and effective
- PCA shows a good reliability for determining valid orientation certainty values
- annual rings close to the pith are more circular
- Blocksize, distribution, amount of blocks and Fourier Spectrum preprocessing are very important for accurate pith estimation